



Nonlinear and Adaptive Control Design

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*A Volume in the Wiley Series on
Adaptive and Learning Systems for Signal Processing,
Communications, and Control*
Simon Haykin, Series Editor

Nonlinear And Adaptive Control Design

Jing Na, Qiang Chen, Xuemei Ren



Nonlinear And Adaptive Control Design:

Nonlinear and Adaptive Control Design Miroslav Krstic, Ioannis Kanellakopoulos, Petar V. Kokotovic, 1995-06-14 Using a pedagogical style along with detailed proofs and illustrative examples this book opens a view to the largely unexplored area of nonlinear systems with uncertainties The focus is on adaptive nonlinear control results introduced with the new recursive design methodology adaptive backstepping Describes basic tools for nonadaptive backstepping design with state and output feedbacks

Nonlinear and Adaptive Control with Applications Alessandro Astolfi, Dimitrios Karagiannis, Romeo Ortega, 2007-12-06 The authors here provide a detailed treatment of the design of robust adaptive controllers for nonlinear systems with uncertainties They employ a new tool based on the ideas of system immersion and manifold invariance New algorithms are delivered for the construction of robust asymptotically stabilizing and adaptive control laws for nonlinear systems The methods proposed lead to modular schemes that are easier to tune than their counterparts obtained from Lyapunov redesign

Nonlinear and Adaptive Control Systems Zhengtao Ding, 2013-04-04 Nonlinear and Adaptive Control Systems treats nonlinear control and adaptive control in a unified framework presenting the major results at a moderate mathematical level suitable for MSc students and engineers with undergraduate degrees

Nonlinear and Adaptive Control Design of Active Suspensions Jung-Shan Lin, 1997

Nonlinear and Adaptive Control Alan S.I. Zinober, David H.

Owens, 2002-09-12 The objective of the EU Nonlinear Control Network Workshop was to bring together scientists who are already active in nonlinear control and young researchers working in this field This book presents selectively invited contributions from the workshop some describing state of the art subjects that already have a status of maturity while others propose promising future directions in nonlinear control Amongst others following topics of nonlinear and adaptive control are included adaptive and robust control applications in physical systems distributed parameter systems disturbance attenuation dynamic feedback optimal control sliding mode control and tracking and motion planning

Adaptive Control Design and Analysis Gang Tao, 2003-07-09 A systematic and unified presentation of the fundamentals of adaptive control theory in both continuous time and discrete time Today adaptive control theory has grown to be a rigorous and mature discipline As the advantages of adaptive systems for developing advanced applications grow apparent adaptive control is becoming more popular in many fields of engineering and science Using a simple balanced and harmonious style this book provides a convenient introduction to the subject and improves one's understanding of adaptive control theory

Adaptive Control Design and Analysis features

- Introduction to systems and control
- Stability operator norms and signal convergence
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- State feedback adaptive control designs
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- Unified continuous and discrete time adaptive control
- L1 a robustness theory for adaptive systems
- Direct and indirect adaptive control designs
- Benchmark comparison study of adaptive control designs
- Multivariate adaptive control
- Nonlinear adaptive control
- Adaptive compensation of actuator nonlinearities
- End of chapter discussion problems and advanced topics

As either a textbook or reference this self contained tutorial of adaptive control design and analysis is ideal for practicing engineers researchers and graduate students alike Adaptive Dual Control Nikolai Michailovich Filatov,Heinz Unbehauen,2004-04-20 This monograph demonstrates how the performance of various well known adaptive controllers can be improved significantly using the dual effect The modifications to incorporate dual control are realized separately and independently of the main adaptive controller without complicating the algorithms A new bicriterial approach for dual control is developed and applied to various types of popular linear and nonlinear adaptive controllers Practical applications of the designed controllers to several real time problems are presented This monograph is the first book providing a complete exposition on the dual control problem from the inception in the early 1960s to the present state of the art aiming at students and researchers in adaptive control as well as design engineers in industry **Identification and Adaptive Control for Nonlinear Systems and Applications** Jianhua Zhang,Yang Li,Qiang Chen,2022-03-15 Identification and Adaptive Control for Nonlinear Systems and Applications Applied Mathematics in Control Engineering introduces nonlinear systems concepts system analysis system control methods and applications in various fields The major contribution of the book includes 1 The basic concepts of nonlinear systems stability analysis and nonlinear systems control method 2 The stability analysis of complex nonlinear system with adaptive neural networks control 3 The nonlinear systems adaptive sliding mode controller design of complex nonlinear systems 4 Some industrial application The book gives an introduction to basic nonlinear systems architectures for adaptive control methods Emphasis is placed on the mathematical analysis of these systems on methods of controlling them for adaptive control and on their application to practical engineering problems in such areas as aircraft path planning This book enables audience to understand the basic architectures of control science and engineering and to master classical and advanced design method for nonlinear system Introduces nonlinear systems concepts system analysis system control methods and applications in various fields Presents basic concepts of nonlinear systems stability analysis and nonlinear systems control method Offers practical examples Nonlinear Adaptive Control Design with Applications ,2005

Stable Adaptive Control and Estimation for Nonlinear Systems Jeffrey T. Spooner,Manfredi Maggiore,Raúl Ordóñez,Kevin M. Passino,2004-03-24 Thema dieses Buches ist die Anwendung neuronaler Netze und Fuzzy Logic Methoden zur Identifikation und Steuerung nichtlinear dynamischer Systeme Dabei werden fortgeschrittene Konzepte der herkömmlichen Steuerungstheorie mit den intuitiven Eigenschaften intelligenter Systeme kombiniert um praxisrelevante Steuerungsaufgaben zu lösen Die Autoren bieten viel Hintergrundmaterial ausgearbeitete Beispiele und Übungsaufgaben helfen Studenten und Praktikern beim Vertiefen des Stoffes Lösungen zu den Aufgaben sowie MATLAB Codebeispiele sind ebenfalls enthalten **System Identification for Control Design** Linda C. Rae,1990 **Adaptive Identification and Control of Uncertain Systems with Non-smooth Dynamics** Jing Na,Qiang Chen,Xuemei Ren,2018-06-12 Adaptive Identification and Control of Uncertain Systems with Nonsmooth Dynamics reports some of the latest research on modeling

identification and adaptive control for systems with nonsmooth dynamics e.g backlash dead zone friction saturation etc The authors present recent research results for the modelling and control designs of uncertain systems with nonsmooth dynamics such as friction dead zone saturation and hysteresis etc with particular applications in servo systems The book is organized into 19 chapters distributed in five parts concerning the four types of nonsmooth characteristics namely friction dead zone saturation and hysteresis respectively Practical experiments are also included to validate and exemplify the proposed approaches This valuable resource can help both researchers and practitioners to learn and understand nonlinear adaptive control designs Academics engineers and graduate students in the fields of electrical engineering control systems mechanical engineering applied mathematics and computer science can benefit from the book It can be also used as a reference book on adaptive control for servo systems for students with some background in control engineering Explains the latest research outputs on modeling identification and adaptive control for systems with nonsmooth dynamics Provides practical application and experimental results for robotic systems and servo motors

Adaptive Control Dianwei Qian, 2018-03 Adaptive control is the control method used by a controller which must adapt to a controlled system with parameters which vary or are initially uncertain An adaptive control system utilizes on line identification of which either system parameter or controller parameter which does not need a priori information about the bounds on these uncertain or time varying parameters These approaches consider their control design in the sense of Lyapunov Besides there are still some branches by combining adaptive control and other control methods i.e nonlinear control methods intelligent control methods and predict control methods to name but a few Addresses some original contributions reporting the latest advances in adaptive control It aims to gather the latest research on state of the art methods applications and research for the adaptive control theory and recent new findings obtained by the technique of adaptive control Apparently the book cannot include all research topics Different aspects of adaptive control are explored Chapters includes some new tendencies and developments in research on a adaptive formation controller for multi robot systems L1 adaptive control design of the the longitudinal dynamics of a hypersonic vehicle model adaptive high gain control of biologically inspired receptor systems adaptive residual vibration suppression of sigid flexible coupled systems neuro hierarchical sliding mode control for under actuated mechanical systems neural network adaptive PID control design based on PLC for a water level system and fuzzy based design of networked control systems with random time delays and packet dropout in the forward communication channel

Nonlinear and Adaptive Control of Model Helicopter, 2006 A helicopter is a complex nonlinear system and also an under actuated system with fewer independent control actuators than degrees of freedom to be controlled making the control difficult There is a growing interest in the modeling and control of such systems using nonlinear dynamic models and nonlinear control Analytical techniques based on Lyapunov theory are then used to design the controller and still the design can become extremely complex Hence the existing control methods use linearization techniques on the actual nonlinear dynamics of the plant and

linear control techniques The resulting performance may not be satisfactory especially when the system is subjected to unknown and sudden disturbances In this thesis we present a new Nonlinear and Adaptive controller design which uses the actual nonlinear model of the helicopter and not a linearized version The design methodology basically involves making the combined dynamics of the helicopter and the controller resemble the dynamics of a nonlinear time varying electrical circuit having the required properties using a process similar to reverse engineering The circuit template in turn is formed from well defined time varying and or nonlinear electrical elements and using proper interconnections The kind of elements used and the general form of the dynamics derived will depend upon the application For example in the helicopter case the closed loop dynamics of the helicopter and the controller expressed in terms of the error variable should point to a NLTV circuit with only passive elements For this the reactive elements should have their relaxation points the points where the stored energy is zero at and only at the origin Also the stored energy should be monotonically increasing We can bring in any knowledge including the structure that we have about the plant being controlled in enhancing the circuit

Adaptive Control of Nonsmooth Dynamic Systems Gang Tao, Frank L. Lewis, 2013-04-17 A complete reference to adaptive control of systems with nonsmooth industrial nonlinearities such as backlash dead zones component failure friction hysteresis saturation and time delays Actuator nonlinearities are ubiquitous in engineering practice and limit control system performance While standard feedback control alone cannot handle these nonsmooth nonlinearities effectively this book shows how such nonlinear characteristics can be compensated for by using adaptive and intelligent control techniques This allows desired system performance to be achieved in the presence of uncertain nonlinearities With surveys of literature and summaries of various design methods the contributors present new solutions to some important issues in adaptive control of systems with various sorts of nonsmooth nonlinearities The book motivates more research activities in the field of adaptive control of nonsmooth nonlinear industrial systems by formulating several challenging open problems in related areas

Nonlinear Control Design Riccardo Marino, 1995-01-01 Nonlinear Control Design presents a self contained introduction to nonlinear feedback control design for continuous time finite dimensional uncertain systems It deals with nonlinear systems affected by uncertainties such as unknown constant parameters time varying disturbances and uncertain nonlinearities Both state feedback and output feedback are addressed Differential geometric techniques are used to identify classes of nonlinear systems considered and to design feedback algorithms Adaptive versions of these controls are developed in the presence of unknown parameters while robust versions are designed in the presence of time varying disturbances These control algorithms are applied to significant physical control problems from electric motor drives robotics aerospace power systems and are illustrated through worked examples The text is illustrated throughout with over 100 exercises more than 75 worked examples and 12 physical examples

Applied Systemic Studies Henry Selvaraj, Takayuki Fujimoto, 2023-03-21 This book is a collection of a wide range of research papers that combine both the humanities and sciences in applied informatics In

particular it is intended for readers interested in the fields of artificial intelligence data science virtual reality and intelligent systems Technologies and findings in artificial intelligence data science virtual reality and intelligent systems are being used in all academic disciplines today This book is a compilation of specific and advanced research findings from a wide range of research fields where they are being applied today The papers included are based on those presented in August 2022 at the International Conference on Systems Engineering ICSEng Tokyo a prestigious academic conference that has been held annually since 1974 The papers have been rigorously reviewed and selected by multiple peer reviewers *Adaptive Control Systems* Gang Feng,Rogelio Lozano,1999-05-10 Adaptive control is no longer just an important theoretical field of study but is also providing solutions to real world problems Adaptive techniques will transform the world of control The leading world practitioners of adaptive control have contributed to this handbook which is the most important work yet in this field Not only are techniques described in theory but detailed control algorithms are given making this a practical cookbook of adaptive control for both control professionals and practising engineers The book presents the most advanced techniques and algorithms of adaptive control These include various robust techniques performance enhancement techniques techniques with less a priori knowledge nonlinear adaptive control techniques and intelligent adaptive techniques Each technique described has been developed to provide a practical solution to a real life problem This volume will therefore not only advance the field of adaptive control as an area of study but will also show how the potential of this technology can be realised and offer significant benefits Practical cookbook of adaptive control Contains important research **Performance of Nonlinear Approximate Adaptive Controllers** Mark French,Csaba Szepesvári,Eric Rogers,2003-06-27 In recent years there has been a wide interest in non linear adaptive control using approximate models either for tracking or regulation and usually under the banner of neural network based control The authors present a unique critical evaluation of the approximate model philosophy and its setting rigorously comparing the performance of such controls against competing designs Analysing a very topical aspect of contemporary research and control practice this book highlights the situations in which approximate model based designs are most appropriate and indicates scenarios in which other designs could be used more productively Throughout the text concepts are illustrated using a variety of examples both academic problems and those based on physical examples The work is designed to open the door to realistic applications Unified coverage of the theory and application of a wide range of control systems areas including neural network based control and control using the approximate model Presents a mathematically well founded introduction to the area of intelligent control A varied selection of practical examples drawn from a variety of fields including robotics and aerospace illustrate theoretical principles Clear comparisons of a variety of control designs Cross disciplinary approach to this leading edge topic A valuable reference for control practitioners and theorists artificial intelligence researchers and applied mathematicians as well as graduate students and researchers with an interest in adaptive control and stability *Adaptive Control Tutorial* Petros Ioannou,Baris Fidan,2006-01-01 Designed to

meet the needs of a wide audience without sacrificing mathematical depth and rigor Adaptive Control Tutorial presents the design analysis and application of a wide variety of algorithms that can be used to manage dynamical systems with unknown parameters Its tutorial style presentation of the fundamental techniques and algorithms in adaptive control make it suitable as a textbook Adaptive Control Tutorial is designed to serve the needs of three distinct groups of readers engineers and students interested in learning how to design simulate and implement parameter estimators and adaptive control schemes without having to fully understand the analytical and technical proofs graduate students who in addition to attaining the aforementioned objectives also want to understand the analysis of simple schemes and get an idea of the steps involved in more complex proofs and advanced students and researchers who want to study and understand the details of long and technical proofs with an eye toward pursuing research in adaptive control or related topics The authors achieve these multiple objectives by enriching the book with examples demonstrating the design procedures and basic analysis steps and by detailing their proofs in both an appendix and electronically available supplementary material online examples are also available A solution manual for instructors can be obtained by contacting SIAM or the authors Preface Acknowledgements List of Acronyms Chapter 1 Introduction Chapter 2 Parametric Models Chapter 3 Parameter Identification Continuous Time Chapter 4 Parameter Identification Discrete Time Chapter 5 Continuous Time Model Reference Adaptive Control Chapter 6 Continuous Time Adaptive Pole Placement Control Chapter 7 Adaptive Control for Discrete Time Systems Chapter 8 Adaptive Control of Nonlinear Systems Appendix Bibliography Index

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