

Multisensor Integration and Fusion for Intelligent Machines and Systems (Computer Engineering & Computer Science)

May, 2004

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J. David Irwin



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Advanced Robotics & Intelligent Machines J. O. Gray, Darwin G. Caldwell, 1996 Advanced robotics describes the use of sensor based robotic devices which exploit powerful computers to achieve the high levels of functionality that begin to mimic intelligent human behaviour The object of this book is to summarise developments in the base technologies survey recent applications and highlight new advanced concepts which will influence future progress

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Data Fusion in Robotics and Machine Intelligence Mongi A. Abidi, 1992 Addresses the techniques for modelling and integration of data provided by different sensors within robotics and knowledge sources within machine intelligence The text aims to give a unified vision of the future of the field presented from both the theoretical and practical angles

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Robotics, Mechatronics and Manufacturing Systems T. Takamori, K. Tsuchiya, 2012-12-02 One of the most important problems in the field of engineering and technology is the development of so called intelligent systems which can perform various intellectual tasks This book is dedicated to the current progress of research in this vast field and specifically explores the topics of robotics mechatronics and manufacturing systems

Multisensor Fusion and Integration for Intelligent Systems Lee Suk-han, Hanseok Ko, Hernsoo Hahn, 2009-05-28 The eld of multi sensor fusion and integration is growing into signi cance as our society is in transition into ubiquitous computing environments with robotics services everywhere under ambient intelligence What surround us are to be the networks of sensors and actuators that monitor our environment health security and safety as well as the service robots intelligent vehicles and autonomous systems of ever heightened autonomy and dependability with integrated heterogeneous sensors and actuators The eld of multi sensor fusion and integration plays key role for m ing the above transition possible by providing fundamental theories and tools for implementation This volume is an edition of the papers selected from the 7th IEEE International Conference on Multi Sensor Integration and Fusion IEEE MFI 08 held in Seoul Korea August 20 22 2008 Only 32 papers out of the 122 papers accepted for IEEE MFI 08 were chosen and requested for revision and extension to be included in this volume The 32 contributions to this volume are organized into three parts Part I is dedicated to the Theories in Data and Information Fusion Part II to the Multi Sensor Fusion and Integration in Robotics and Vision and Part III to the Applications to Sensor Networks and Ubiquitous Computing Environments To help readers understand better a part summary is included in each part as an introduction The summaries of Parts I II and III are prepared respectively by Prof Hanseok Ko Prof Sukhan Lee and Prof Hernsoo Hahn *IECON '90:*

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Manufacturing Review ,1993 **Autonomous Mobile Robots: Perception, mapping, and navigation** Sundararaja S. Iyengar,Alberto Elfes,1991 *McGraw-Hill Yearbook of Science and Technology* ,1992

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