

World Scientific Series in Robotics and Automated Systems – Vol. 2

PARALLEL COMPUTATION SYSTEMS FOR ROBOTICS

Algorithms and Architectures

edited by

A. Fijany and A. Bejczy

World Scientific

Parallel Computation Systems For Robotics Algorithms And Architectures

Roman Wölfel

Parallel Computation Systems For Robotics Algorithms And Architectures:

Parallel Computation Systems For Robotics: Algorithms And Arch. Amir Fijany,Antal K Bejczy,1992-08-31 This book presents an extensive survey of the state of the art research in parallel computational algorithms and architectures for robot manipulator control and simulation It deals not only with specifics but also includes general and broader issues which serve as a useful foundation to the topic The educational flavor of the book makes it a necessary resource for researchers engineers and students wanting to be familiarized with the potential offered by the application of parallel processing to robotic problems and its current issues and trends

Parallel Computation Systems for Robotics A. Fijany,A.

Bejczy,1992 *Control and Dynamic Systems V40: Advances in Robotic Systems Part 2 of 2* C.T. Leonides,2012-12-02

Advances in Robotic Systems Part 2 is the second of a companion set of two volumes on advances in robotic systems dynamics and control This book comprises nine chapters with the first focusing on kinesthetic feedback techniques in teleoperated systems The succeeding chapters then delve into topics such as parallel algorithms and fault tolerant reconfigurable architecture for robot kinematics and dynamics computations trajectory planning for robot control and a control systems perspective Other chapters cover simplified techniques for adaptive control of robotic systems theory and applications of configuration control for redundant manipulators nonlinear feedback for force control of robot manipulators systolic architectures for dynamic control of manipulators inverse dynamics and forward dynamics This book will be of interest to practitioners in the fields of computer science systems science and mathematics

Sensor-Based Robots:

Algorithms and Architectures C.S.George Lee,2012-12-06 Most industrial robots today have little or no sensory capability Feedback is limited to information about joint positions combined with a few interlock and timing signals These robots can function only in an environment where the objects to be manipulated are precisely located in the proper position for the robot to grasp i.e. in a structured environment For many present industrial applications this level of performance has been adequate With the increasing demand for high performance sensor based robot manipulators in assembly tasks meeting this demand and challenge can only be achieved through the consideration of 1 efficient acquisition and processing of internal sensory information 2 utilization and integration of sensory information from various sensors tactile force and vision to acquire knowledge in a changing environment 3 exploitation of inherent robotic parallel algorithms and efficient VLSI architectures for robotic computations and finally 4 system integration into a working and functioning robotic system This is the intent of the Workshop on Sensor Based Robots Algorithms and Architectures to study the fundamental research issues and problems associated with sensor based robot manipulators and to propose approaches and solutions from various viewpoints in improving present day robot manipulators in the areas of sensor fusion and integration sensory information processing and parallel algorithms and architectures for robotic computations

AIAA Computing in Aerospace ... Conference , Scientific and Technical Aerospace Reports ,1990 *Proceedings of the IEEE International*

Symposium on Industrial Electronics ,1997 Algorithms and Architectures for Real-Time Control 1998 D.F. Garcia Nocetti,1998-09-10 The 5th IFAC Workshop on Algorithms and Architectures for Real Time Control AARTC 98 was organized under the auspices of the IFAC Technical Committee This Committee is concerned with the use of emerging software and hardware developments in real time control The AARTC 98 Technical Programme consisted of seventeen sessions covering major areas of software hardware and applications for real time control namely robotics modeling and control software design tools and methodologies industrial process control and manufacturing systems parallel and distributed systems non linear control systems neural networks parallel and distributed algorithms for real time signal processing and control transport applications algorithms fault tolerant systems and fuzzy control The contributions were selected from a large number of high quality full draft papers and late breaking paper contributions presenting very recent research work

Whitaker's Books in Print ,1998 **International Books in Print, 1995** Barbara Hopkinson,[Anonymus AC01401231],1995 **Algorithms and Architectures for Real-time Control 1997, AARTC '97** António E. Ruano,Peter J. Fleming,1997 These proceedings contain the selection of papers presented at the IFAC Workshop on Algorithms and Architectures for Real Time Control AARTC 97 held at the Vilamoura Marina Hotel Vilamoura Portugal Rapid developments in microelectronics and computer science continue to provide opportunities for real time control engineers to address new challenges New opportunities arise from such diverse directions as ever increasing system complexity and sophistication environmental legislation economic competition safety and reliability These are typical themes which were highlighted at the IFAC AARTC 97 Workshop The AARTC 97 Final Programme consisted of 22 sessions covering major areas of software hardware and applications for real time control Important topics were soft computing methods software tools and architectures embedded systems parallel and distributed systems architectures custom processors algorithms estimation methods neural networks fuzzy methods PID controllers transport applications industrial process control robotics and discrete event and hybrid systems

ISIE ... ,1997 *Forthcoming Books* Rose Arny,1992-10 **Control and Dynamic Systems** C. T. Leondes,1991 IEEE Computer Society Workshop on Computer Architecture for Pattern Analysis and Image Database Management ,1985 **Artificial Intelligence Abstracts** ,1991 **1985 IEEE Computer Society Workshop on Computer Architecture for Pattern Analysis and Image Database Management, Miami Beach, Florida, November 18-20, 1985** ,1985 **Peterson's Graduate Programs in Engineering and Applied Sciences, 1996** Peterson's Guides,Peterson's Guides Staff,Peterson's,1995-12-10 Graduate students depend on this series and ask for it by name Why For over 30 years it's been the only one stop source that supplies all of their information needs The new editions of this six volume set contain the most comprehensive information available on more than 1 500 colleges offering over 31 000 master's doctoral and professional degree programs in more than 350 disciplines New for 1997 Non degree granting research centers institutes and training programs that are part of a graduate degree program Five discipline

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