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Biswa Nath Datta

Numerical Methods For Linear Control Systems

Norman Lang



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Computational Aspects of Linear Control Claude Brezinski, 2013-12-01 Many devices we say dynamical systems or simply systems behave like black boxes they receive an input this input is transformed following some laws usually a differential equation and an output is observed The problem is to regulate the input in order to control the output that is for obtaining a desired output Such a mechanism where the input is modified according to the output measured is called feedback The study and design of such automatic processes is called control theory As we will see the term system embraces any device and control theory has a wide variety of applications in the real world Control theory is an interdisciplinary domain at the junction of differential and difference equations system theory and statistics Moreover the solution of a control problem involves many topics of numerical analysis and leads to many interesting computational problems linear algebra QR SVD projections Schur complement structured matrices localization of eigenvalues computation of the rank Jordan normal form Sylvester and other equations systems of linear equations regularization etc root localization for polynomials inversion of the Laplace transform computation of the matrix exponential approximation theory orthogonal polynomials Padé approximation continued fractions and linear fractional transformations optimization least squares dynamic programming etc So control theory is also a good excuse for presenting various sometimes unrelated issues of numerical analysis and the procedures for their solution This book is not a book on control

Linear Control System Analysis and Design with MATLAB Constantine H. Houptis, Stuart N. Sheldon, 2013-10-30 This book uses numerous in depth explanations diagrams calculations and tables to provide an intensive overview of modern control theory and control system design Mathematics is kept to a minimum and engineering applications are stressed

throughout Completely updated and packed with student friendly features the sixth edition presents a range of updated examples using MATLAB as well as an appendix listing MATLAB functions for optimizing control system analysis and design Over 75 percent of the problems presented in the previous edition have been revised or replaced

Numerical Methods for Large-Scale Linear Time-Varying Control Systems and related Differential Matrix Equations Norman Lang, 2018 This thesis is concerned with the linear quadratic optimal control and model order reduction MOR of large scale linear time varying LTV control systems In the first two parts particular attention is paid to a tracking type finite time optimal control problem with application to an inverse heat conduction problem and the balanced truncation BT MOR method for LTV systems In both fields of application the efficient solution of differential matrix equations DMEs is of major importance The third and largest part deals with the application of implicit time integration methods to these matrix valued ordinary differential equations In this context in particular the rather new class of peer methods is introduced Further for the efficient solution of large scale DMEs in practice low rank solution strategies are inevitable Here low rank time integrators based on a symmetric indefinite factored representation of the right hand sides and the solution approximations of the DMEs are presented In contrast to the classical low rank Cholesky type factorization this avoids complex arithmetic and tricky implementations and algorithms Both low rank approaches are compared for numerous implicit time integration methods

Computational Methods for Linear Control Systems Petko Hr. Petkov, Nikolai D. Christov, Mihail M. Konstantinov, 1991-01-01

Numerical Linear Algebra Techniques for Systems and Control IEEE Control Systems Society, 1994 A reprint collection of practical papers covering the broad scope of numerical linear algebra in computer aided control system design software Between the 35 page introduction and extensive 21 page bibliography are seven sections general numerical issues in control controllability observability and realizations closeness problems frequency response transfer functions poles and zeros pole assignment and observer design Riccati Lyapunov and Sylvester equations and some relevant results from numerical linear algebra Annotation copyright by Book News Inc Portland OR

Large-Scale Scientific Computing Ivan Lirkov, Svetozar D. Margenov, Jerzy Wasniewski, 2009-03-26 Coverage in this proceedings volume includes robust multilevel and hierarchical preconditioning methods applications for large scale computations and optimization of coupled engineering problems and applications of metaheuristics to large scale problems

University of Michigan Official Publication University of Michigan, 1988 Each number is the catalogue of a specific school or college of the University

Scientific and Technical Aerospace Reports, 1980

College of Engineering University of Michigan. College of Engineering, 1987

Bilinear Control Systems David Elliott, 2009-09-01 The mathematical theory of control became a eld of study half a century ago in attempts to clarify and organize some challenging practical problems and the methods used to solve them It is known for the breadth of the mathematics it uses and its cross disciplinary vigor Its literature which can be found in Section 93 of Mathematical Reviews was at one time dominated by the theory of linear control systems which

mathematically are described by linear differential equations forced by additive control inputs. That theory led to well regarded numerical and symbolic computational packages for control analysis and design. Nonlinear control problems are also important in these either the underlying dynamical system is nonlinear or the controls are applied in an additive way. The last four decades have seen the development of theoretical work on nonlinear control problems based on differential manifold theory, nonlinear analysis and several other mathematical disciplines. Many of the problems that had been solved in linear control theory plus others that are new and distinctly nonlinear have been addressed. Some resulting general definitions and theorems are adapted in this book to the bilinear case.

A Study of Algorithms in Linear Control Theory I. S. Pace, 1973
CONTROL ALGORITHMS NUMERICAL METHODS MULTIVARIABLE SYSTEMS LINEAR SYSTEMS CONTROL SYSTEMS ANALYSIS CONTROL DIFFERENTIAL EQUATIONS STABILITY ROOTS OF EQUATIONS MATRICES **Applied Mechanics Reviews**, 1978

Control Perspectives on Numerical Algorithms and Matrix Problems Amit Bhaya, Eugenius Kaszkurewicz, 2006-03-01. This book organizes the analysis and design of iterative numerical methods from a control perspective. A variety of applications are discussed including iterative methods for linear and nonlinear systems of equations, neural networks for linear and quadratic programming problems and integration and shooting methods for ordinary differential equations.

Journal of Dynamic Systems, Measurement, and Control, 2001. Publishes theoretical and applied original papers in dynamic systems. Theoretical papers present new theoretical developments and knowledge for controls of dynamical systems together with clear engineering motivation for the new theory. Applied papers include modeling, simulation and corroboration of theory with emphasis on demonstrated practicality.

Optimization of Linear Control Systems F. A. Aliev, V. B. Larin, 1998-11-19. The authors present analytical methods for synthesis of linear stationary and periodical optimal controlled systems and create effective computational algorithms for synthesis of optimal regulators and filters. The procedures of Youla, Jabr, Bongiorno 1976 and Desoer, Lin, Murray, Saeks 1980 are special cases of this procedure. The monograph also includes original computational algorithms, solutions of usual and generalized Lyapunov and Riccati equations, polynomial matrix factorization and illustrates the effectiveness of these algorithms by examples in the field of numerical methods for optimization of linear controlled systems.

Modern Control System Theory and Design Stanley M. Shinnars, 1992-03-25. Offers unified treatment of conventional and modern continuous and discrete control theory and demonstrates how to apply the theory to realistic control system design problems. Along with linear and nonlinear digital and optimal control systems, it presents four case studies of actual designs. The majority of solutions contained in the book and the problems at the ends of the chapters were generated using the commercial software package MATLAB and is available free to the users of the book by returning a postcard contained with the book to the MathWorks Inc. This software also contains the following features: utilities created to enhance MATLAB and several of the MathWorks toolboxes; Tutorial File which contains the essentials necessary to understand the MATLAB interface; other books require additional books for full

comprehension Demonstration m file which gives the users a feel for the various utilities included OnLine HELP Synopsis File which reviews and highlights the features of each chapter

Control and Dynamic Systems V56: Digital and Numeric Techniques and Their Application in Control Systems C.T. Leonides, 2012-12-02 Control and Dynamic Systems Advances in Theory and Applications Volume 56 Digital and Numeric Techniques and their Applications in Control Systems Part 2 of 2 covers the significant developments in digital and numerical techniques for the analysis and design of modern complex control systems This volume is composed of 12 chapters and starts with a description of the design techniques of linear constrained discrete time control systems The subsequent chapters describe the techniques dealing with robust real time system identification the adaptive control algorithms and the utilization of methods from generalized interpolation and operator theory to deal with a wide range of problems in robust control These topics are followed by reviews of the decentralized control design for interconnected uncertain systems the computation of frequency response of descriptor systems by rational interpolation the techniques for the synthesis of multivariable feedback control laws and the effect of the initial condition in state estimation for discrete time linear systems Other chapters illustrate practical efficient and reliable numerical algorithms for robust multivariable control design of linear time invariant systems as well as a complete analysis of closed loop transfer recovery in discrete time systems using observer based controllers The last chapters provide the techniques in robust policy making in the global economic environment and the implications of robust control techniques for continuous time systems This book will prove useful to process control systems and design engineers

U.S. Government Research & Development Reports, 1970

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